

In-Class Final Exam Review Set A, Math 1554, Fall 2019

1. Indicate whether the statements are true or false.

	true	false	
			$Ax = b$
<input checked="" type="radio"/>	<input type="radio"/>		If a linear system has more unknowns than equations , then the system has either no solutions or infinitely many solutions.
<input type="radio"/>	<input checked="" type="radio"/>		A $n \times n$ matrix A and its echelon form E will always have the same eigenvalues.
<input checked="" type="radio"/>	<input type="radio"/>		$x^2 - 2xy + 4y^2 \geq 0$ for all real values of x and y .
<input checked="" type="radio"/>	<input type="radio"/>		If matrix A has linearly dependent columns, then $\dim((\text{Row } A)^\perp) > 0$.
<input checked="" type="radio"/>	<input type="radio"/>		If λ is an eigenvalue of A , then $\dim(\text{Null}(A - \lambda I)) > 0$.
<input checked="" type="radio"/>	<input type="radio"/>		If A has QR decomposition $A = QR$, then $\text{Col } A = \text{Col } Q$.
<input checked="" type="radio"/>	<input type="radio"/>		If A has LU decomposition $A = LU$, then $\text{rank}(A) = \text{rank}(U)$.
<input checked="" type="radio"/>	<input type="radio"/>		If A has LU decomposition $A = LU$, then $\dim(\text{Null } A) = \dim(\text{Null } U)$.

$\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
 $\text{Null}(A)$

2. Give an example of the following.

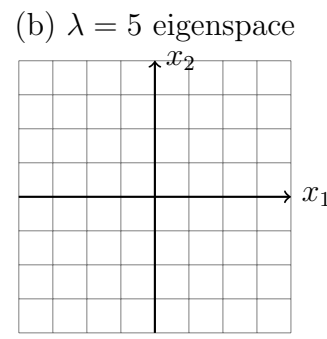
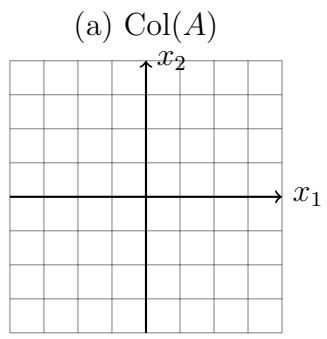
i) A 4×3 lower triangular matrix, A , such that $\text{Col}(A)^\perp$ is spanned by

the vector $\vec{v} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 1 \end{pmatrix}$. $A = \begin{pmatrix} & & & \\ & & & \\ & & & \\ & & & \end{pmatrix}$ $\text{Col}(A) = \{ \vec{x} : \vec{x} \cdot \vec{v} = 0 \}$
 $x_1 + 2x_2 + 3x_3 + x_4 = 0$

ii) A 3×4 matrix A , that is in RREF, and satisfies $\dim((\text{Row } A)^\perp) = 2$ and $\dim((\text{Col } A)^\perp) =$

2. $A = \begin{pmatrix} & & & \\ & & & \\ & & & \end{pmatrix}$

3. (3 points) Suppose $A = \begin{pmatrix} 3 & 1 \\ 6 & 2 \end{pmatrix}$. On the grid below, sketch a) $\text{Col}(A)$, and b) the eigenspace corresponding to eigenvalue $\lambda = 5$.



$$\vec{x} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$Q(\vec{x}) = 0x^2 - 2xy + 4y^2 = \underbrace{\vec{x}^T \cdot A \cdot \vec{x}}_{\geq 0} \geq 0 \quad \forall \vec{x}$$

$$A = \begin{bmatrix} 1 & -1 \\ -1 & 4 \end{bmatrix}$$

Q is positive s.d

$$\lambda^2 - (1+4)\lambda + (1 \cdot 4 - (-1)) = 0 \quad \lambda \geq 0$$

$$\lambda^2 - 5\lambda + 3 = 0 = (\lambda - \lambda_1)(\lambda - \lambda_2)$$

$$\lambda = \frac{5 \pm \sqrt{-1}}{2} = \lambda^2 - (\lambda_1 + \lambda_2)\lambda + \lambda_1 \cdot \lambda_2$$

$$\lambda_1 + \lambda_2 = 5$$

$$\lambda_1 \cdot \lambda_2 = 3$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$

$$\lambda^2 - (a+d)\lambda + (ad-bc) = 0$$

$$\begin{aligned} x^2 - 2xy + 4y^2 &= (x^2 - 2xy + y^2) + 3y^2 \\ &= \underbrace{(x-y)^2}_{\geq 0} + \underbrace{3y^2}_{\geq 0} \geq 0 \end{aligned}$$

T/F

If

A

then

B

True :

False :

Counter example

satisfies A

not B

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$v = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix},$$

basis for $(\text{Span } v)^2$

$$A = [x_1 \dots x_n]$$

$$\downarrow \text{G-S}$$

$$R = \begin{bmatrix} x_1 \cdot u_1 & u_2 \cdot x_1 & \dots \\ & u_2 \cdot x_2 & \dots \\ & & \dots \\ & & & 0 \end{bmatrix}$$

$$Q = [u_1 \dots u_n] \text{ orthonormal}$$

$$\text{Span of } \{x_1\} = \text{Span of } \{u_1\}$$

$$\text{Span of } \{x_1, x_2\} = \text{Span of } \{u_1, u_2\}$$

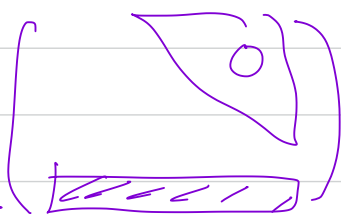
⋮

$$\text{Col}(A) = \text{Span of } \{x_1, \dots, x_n\} = \text{Span of } \{u_1, \dots, u_n\} = \text{Col}(Q)$$

$$\Rightarrow \text{Col}(A) = \left\{ \vec{x} : \underline{x_1 + 2x_2 + 3x_3 + x_4 = 0} \right\}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ -3 \end{bmatrix}$$

$$-x_1 - 2x_2 - 3x_3$$



Lower triangular

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ -x_1 - 2x_2 - 3x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \\ 0 \\ -x_1 \end{bmatrix} + \begin{bmatrix} 0 \\ x_2 \\ 0 \\ -2x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ x_3 \\ -3x_3 \end{bmatrix}$$

$$= x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ -2 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ -3 \end{bmatrix}$$

4. Fill in the blanks.

(a) If $A \in \mathbb{R}^{M \times N}$, $M < N$, and $A\vec{x} = 0$ does not have a non-trivial solution, how many pivot columns does A have?

(b) Consider the following linear transformation.

$$T(x_1, x_2) = (2x_1 - x_2, 4x_1 - 2x_2, x_2 - 2x_1).$$

The domain of T is . The image of $\vec{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ under $T(\vec{x})$ is $\begin{pmatrix} \\ \\ \end{pmatrix}$. The co-domain of T is . The range of T is:

5. Four points in \mathbb{R}^2 with coordinates (t, y) are $(0, 1)$, $(\frac{1}{4}, \frac{1}{2})$, $(\frac{1}{2}, -\frac{1}{2})$, and $(\frac{3}{4}, -\frac{1}{2})$. Determine the values of c_1 and c_2 for the curve $y = c_1 \cos(2\pi t) + c_2 \sin(2\pi t)$ that best fits the points. Write the values you obtain for c_1 and c_2 in the boxes below.

$$c_1 = \text{} \quad c_2 = \text{}$$

In-Class Final Exam Review Set B, Math 1554, Fall 2019

1. Indicate whether the statements are true or false.

true false

- For any vector $\vec{y} \in \mathbb{R}^2$ and subspace W , the vector $\vec{v} = \vec{y} - \text{proj}_W \vec{y}$ is orthogonal to W .
- If A is $m \times n$ and has linearly dependent columns, then the columns of A cannot span \mathbb{R}^m .
- If a matrix is invertible it is also diagonalizable.
- If E is an echelon form of A , then $\text{Null } A = \text{Null } E$.
- If the SVD of $n \times n$ singular matrix A is $A = U\Sigma V^T$, then $\text{Col}A = \text{Col}U$.
- If the SVD of $n \times n$ matrix A is $A = U\Sigma V^T$, $r = \text{rank}A$, then the first r columns of V give a basis for $\text{Null}A$.
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2. Give an example of:

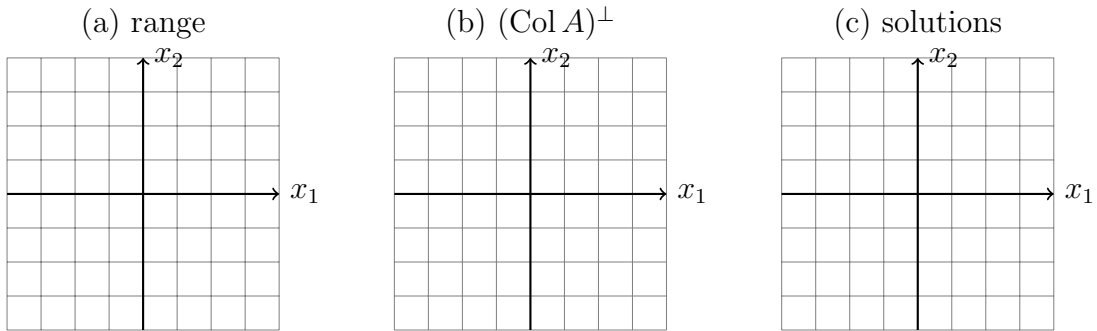
a) a vector $\vec{u} \in \mathbb{R}^3$ such that $\text{proj}_{\vec{p}} \vec{u} = \vec{p}$, where $\vec{u} \neq \vec{p}$, and $\vec{p} = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$: $\vec{u} = \begin{pmatrix} \\ \\ \end{pmatrix}$

b) an upper triangular 4×4 matrix A that is in RREF, 0 is its only eigenvalue, and its corresponding eigenspace is 1-dimensional. $A = \begin{pmatrix} & & & \\ & & & \\ & & & \\ & & & \end{pmatrix}$

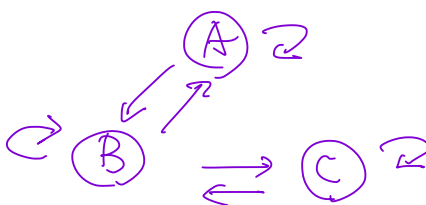
c) A 3×4 matrix, A , and $\text{Col}(A)^\perp$ is spanned by $\begin{pmatrix} 1 \\ -3 \\ -4 \end{pmatrix}$.

d) A 2×2 matrix in RREF that is diagonalizable and not invertible.

3. Suppose $A = \begin{pmatrix} 2 & -1 \\ 4 & -2 \end{pmatrix}$. On the grid below, sketch a) the range of $x \rightarrow Ax$, b) $(\text{Col } A)^\perp$, (c) set of solutions to $A\vec{x} = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$.



4. Matrix A is a 2×2 matrix whose eigenvalues are $\lambda_1 = \frac{1}{2}$ and $\lambda_2 = 1$, and whose corresponding eigenvectors are $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$. Calculate
1. $A(\vec{v}_1 + 4\vec{v}_2)$
 2. A^{10}
 3. $\lim_{k \rightarrow \infty} A^k(\vec{v}_1 + 4\vec{v}_2)$



In-Class Final Exam Review Set C, Math 1554, Fall 2019

1. Indicate whether the statements are possible or impossible.

possible impossible

 $Q(\vec{x}) = \vec{x}^T A \vec{x}$ is a positive definite quadratic form, and $Q(\vec{v}) = 0$, where \vec{v} is an eigenvector of A .

 The maximum value of $Q(\vec{x}) = ax_1^2 + bx_2^2 + cx_3^2$, where $a > b > c$, for $\vec{x} \in \mathbb{R}^3$, subject to $\|\vec{x}\| = 1$, is not unique.

 The location of the maximum value of $Q(\vec{x}) = ax_1^2 + bx_2^2 + cx_3^2$, where $a > b > c$, for $\vec{x} \in \mathbb{R}^3$, subject to $\|\vec{x}\| = 1$, is not unique.

$$\frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 1 \end{pmatrix} = P$$

 A is 2×2 , the algebraic multiplicity of eigenvalue $\lambda = 0$ is 1, and $\dim(\text{Col}(A)^\perp)$ is equal to 0.

 Stochastic matrix P has zero entries and is regular.

P^k has no zero entries for some k .

 A is a square matrix that is not diagonalizable, but A^2 is diagonalizable.

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

 The map $T_A(\vec{x}) = A\vec{x}$ is one-to-one but not onto, A is $m \times n$, and $m < n$.

2. Transform $T_A = A\vec{x}$ reflects points in \mathbb{R}^2 through the line $y = 2 + x$. Construct a standard matrix for the transform using homogeneous coordinates. Leave your answer as a product of three matrices.

3. Fill in the blanks.

- (a) $T_A = A\vec{x}$, where $A \in \mathbb{R}^{2 \times 2}$, is a linear transform that first rotates vectors in \mathbb{R}^2 clockwise by $\pi/2$ radians about the origin, then reflects them through the line $x_1 = x_2$. What is the value of $\det(A)$?
- (b) B and C are square matrices with $\det(BC) = -5$ and $\det(C) = 2$. What is the value of $\det(B)\det(C^4)$?
- (c) A is a 6×4 matrix in RREF, and $\text{rank}(A) = 4$. How many different matrices can you construct that meet these criteria?
- (d) $T_A = A\vec{x}$, where $A \in \mathbb{R}^{2 \times 2}$, projects points onto the line $x_1 = x_2$. What is an eigenvalue of A equal to?
- (e) If an eigenvalue of A is $\frac{1}{3}$, what is one eigenvalue of A^{-1} equal to?
- (f) If A is 30×12 and $A\vec{x} = \vec{b}$ has a **unique least squares solution** \hat{x} for every \vec{b} in \mathbb{R}^{30} , the dimension of $\text{Null}A$ is .

4. A is a 2×2 matrix whose nullspace is the line $x_1 = x_2$, and $C = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$. Sketch the nullspace of $Y = AC$.

5. Construct an SVD of $A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$. Use your SVD to calculate the condition number of A .